

REPORT DOCUMENTATION PAGE				Form Approved OMB No. 0704-0188	
<p>The public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing the burden, to the Department of Defense, Executive Services and Communications Directorate (0704-0188). Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to any penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.</p> <p><b>PLEASE DO NOT RETURN YOUR FORM TO THE ABOVE ORGANIZATION.</b></p>					
1. REPORT DATE (DD-MM-YYYY) 12-10-2009		2. REPORT TYPE Journal Article		3. DATES COVERED (From - To)	
4. TITLE AND SUBTITLE Validation and Intercomparison Studies Within GODAE				5a. CONTRACT NUMBER	
				5b. GRANT NUMBER	
				5c. PROGRAM ELEMENT NUMBER 0601153N	
				5d. PROJECT NUMBER	
6. AUTHOR(S) F. Hernandez, L. Bertino, G. Brassington, E. Chassignet, J. Cummings, F. Davidson, M. Drevillon, G. Garric, M. Kamachi, J. Lellouche, R. Mahdon, M. Martin, A. Ratsimandresy, C. Regnier				5e. TASK NUMBER	
				5f. WORK UNIT NUMBER 73-8677-A8-5	
				7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) Naval Research Laboratory Oceanography Division Stennis Space Center, MS 39529-5004	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES) Office of Naval Research 800 N. Quincy St. Arlington, VA 22217-5660				B. PERFORMING ORGANIZATION REPORT NUMBER NRL/JA/7320-09-9126	
				10. SPONSOR/MONITOR'S ACRONYM(S) ONR	
11. SPONSOR/MONITOR'S REPORT NUMBER(S)				12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release, distribution is unlimited.	
13. SUPPLEMENTARY NOTES					
14. ABSTRACT <p>During the Global Ocean Data Assimilation Experiment (GODAE), seven international operational centers participated in a dedicated modeling system intercomparison exercise from February to April 2008. The objectives were: (1) to show GODAE global-ocean and basin-scale forecasting systems of different countries in routine interaction and continuous operation, (2) to assess the quality and perform scientific validation of the ocean analyses and the forecasting performance of each system, and (3) to learn from this exercise in order to increase interoperability and collaboration in real time. The validation methodology has steadily improved through several validation experiments and projects performed within the operational oceanography community. It relies on common approaches and standardization of outputs, with a set of diagnostics based on fully detailed metrics that characterize its strengths and weaknesses, but it also provides error levels for ocean estimates. The ocean forecasting systems provide daily fields of mesoscale water mass distribution and ocean circulation, with an option for sea-ice variations. We present a subset of the intercomparisons performed over different areas, showing general ocean circulation in agreement with known patterns. We also present some accuracy assessments through comparison with observed data.</p>					
15. SUBJECT TERMS MERSEA, Hybrid Coordinate Ocean Model, atmospheric forcing					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT  UL	18. NUMBER OF PAGES  16	19a. NAME OF RESPONSIBLE PERSON James Cummings
a. REPORT Unclassified	b. ABSTRACT Unclassified	c. THIS PAGE Unclassified			19b. TELEPHONE NUMBER (Include area code) 831-656-5021

20091228154

## PUBLICATION OR PRESENTATION RELEASE REQUEST

Pubkey: 6109

NRLINST 5600.2

1. REFERENCES AND ENCLOSURES	2. TYPE OF PUBLICATION OR PRESENTATION	3. ADMINISTRATIVE INFORMATION
Ref: (a) NRL Instruction 5600.2 (b) NRL Instruction 5510.40D  Encl: (1) Two copies of subject paper (or abstract)	<input type="checkbox"/> Abstract only, published <input type="checkbox"/> Book <input type="checkbox"/> Conference Proceedings (refereed) <input checked="" type="checkbox"/> Invited speaker <input checked="" type="checkbox"/> Journal article (refereed) <input type="checkbox"/> Oral Presentation, published <input type="checkbox"/> Other, explain	<input type="checkbox"/> Abstract only, not published <input checked="" type="checkbox"/> Book chapter <input type="checkbox"/> Conference Proceedings (not refereed) <input type="checkbox"/> Multimedia report <input type="checkbox"/> Journal article (not refereed) <input type="checkbox"/> Oral Presentation, not published
		STRN <u>NRLJA7320-09-9128</u> Route Sheet No. <u>7320/</u> Job Order No. <u>73-8677-A8-5</u> Classification <input checked="" type="checkbox"/> X <input type="checkbox"/> U <input type="checkbox"/> C Sponsor <u>ONR</u> approval obtained <input type="checkbox"/> yes <input checked="" type="checkbox"/> no

## 4. AUTHOR

Title of Paper or Presentation

Validation and Intercomparison Studies Within GODAE

Author(s) Name(s) (First, MI, Last), Code, Affiliation if not NRL

Fabrice Hernandez, Laurent Bertino, G. Brassington, Eric Chassignet, James A. Cummings, Fraser Davidson, M. Drevillon, Gilles Garric, Masafumi Kamachi, J. M. Lellouche, Ray Mahdon, Matthew Martin, Andry Ratsimandresy, Charly Regnier

It is intended to offer this paper to the

(Name of Conference)

(Date, Place and Classification of Conference)

and/or for publication in Oceanography Magazine - Special Issue on GODAE,

(Name and Classification of Publication)

(Name of Publisher)

After presentation or publication, pertinent publication/presentation data will be entered in the publications data base, in accordance with reference (a).

It is the opinion of the author that the subject paper (is     ) (is not ☒ X) classified, in accordance with reference (b).

This paper does not violate any disclosure of trade secrets or suggestions of outside individuals or concerns which have been communicated to the Laboratory in confidence. This paper (does     ) (does not ☒ X) contain any militarily critical technology.

This subject paper (has     ) (has never ☒ X) been incorporated in an official NRL Report.

James A. Cummings, 7321

Name and Code (Principal Author)

*Charles Barron for Cummings*  
 (Signature)

## 5. ROUTING/APPROVAL

CODE	SIGNATURE	DATE	COMMENTS
Author(s) <i>Cummings</i>	<i>Charles Barron for Cummings</i>	<i>3/2/09</i>	Need by <u>10 Apr 09</u>
			Publicly accessible sources used for this publication
Section Head <i>Barron</i>	<i>Charles Barron</i>	<i>3/2/09</i>	
Branch Head Gregg A. Jacobs, 7320	<i>Gregg Jacobs</i>	<i>3/20/09</i>	
Division Head Ruth H. Preller, 7300	<i>Ruth Preller</i>	<i>3/20/09</i>	1. Release of this paper is approved. 2. To the best knowledge of this Division, the subject matter of this paper (has <u>    </u> ) (has never <input checked="" type="checkbox"/> X) been classified.
Security, Code 1226			1. Paper or abstract was released. 2. A copy is filed in this office. <i>55C 94-9</i>
Office of Counsel, Code 1008.3	<i>William for Grand Bude</i>	<i>4/1/09</i>	
ADOR/Director NCST E. R. Franchi, 7000			
Public Affairs (Unclassified/ Unlimited Only), Code 7030.4	<i>Carolyn L. Gilson</i>	<i>4/6/09</i>	
Division, Code			
Author, Code			



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09.1226.1141

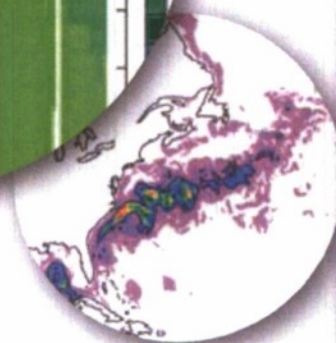
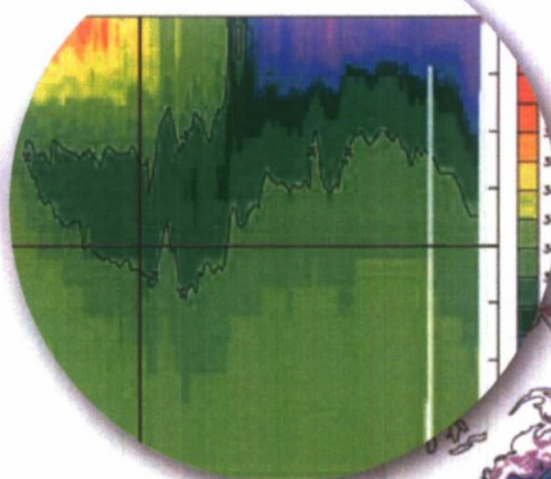
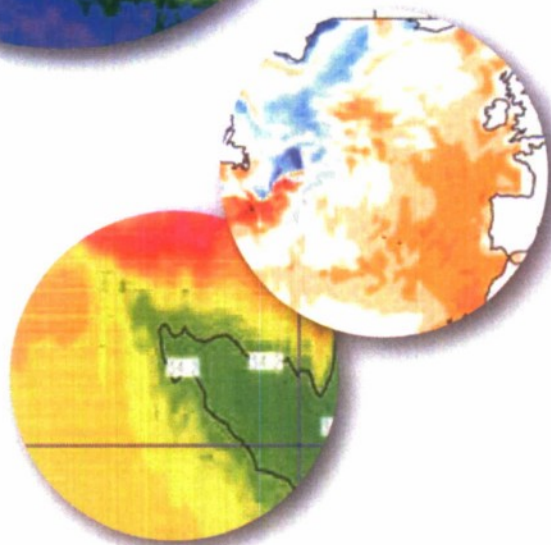
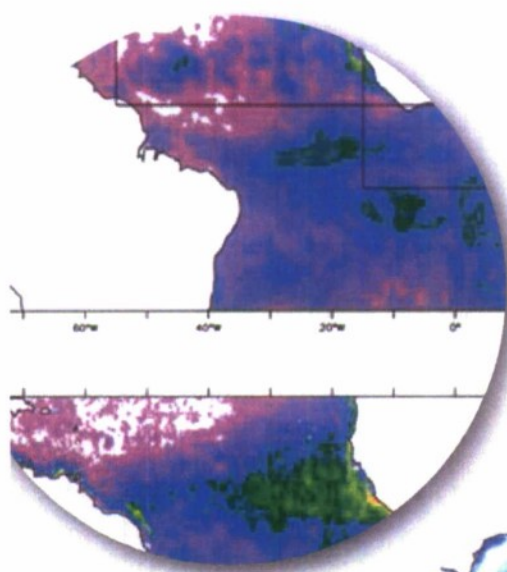
1. REFERENCES AND ENCLOSURES	2. TYPE OF PUBLICATION OR PRESENTATION	3. ADMINISTRATIVE INFORMATION	
<input type="checkbox"/> Abstract only published <input type="checkbox"/> Book chapter <input type="checkbox"/> Conference Proceedings prepared <input type="checkbox"/> Printed special <input checked="" type="checkbox"/> Journal article related <input type="checkbox"/> Oral Presentation published <input type="checkbox"/> Other, explain:	<input type="checkbox"/> Abstract only prepared <input type="checkbox"/> Book chapter <input type="checkbox"/> Conference Proceedings not related <input type="checkbox"/> Multimedia report <input type="checkbox"/> Journal article not related <input type="checkbox"/> Oral Presentation not published	ETRN: NRLJA/7320-09-9125 Route Sheet No. 7320 Son Order No. 73-8677-A8-5 Classification: X Sponsor: ONR Approval date:	
<b>4. AUTHOR</b> Title of Paper or Presentation: Validation and Intercomparison Studies Within GODAE Authors: Hernandez, Laurent; Bertino, G.; Brassington, Eric; Chassignot, James A.; Cummings, Fraser; Davidson, M.; Drevillon, Gilles; Garric, Masafumi; Kamachi, J. M.; Lellouche, Ray; Mahdon, Matthew; Martin, Andry; Ratsimandrasay, Charly; Regnier Was intended to offer this paper to the: (Name of Conference) (Date, Place and Classification of Conference) And/or for publication in: Oceanography Magazine - Special Issue on GODAE (Name and Classification of Publication) (Name of Publication) After presentation or publication, pertinent publication/presentation data will be entered in the publications data base in accordance with reference to: 1. the opinion of the author that the subject paper is (is not) classified in accordance with reference to: 2. the opinion of the sponsor any disclosure of trade secrets or suggestions of outside individuals or concerns which have been incorporated into the publication/presentation. This paper (does) (does not) contain any military critical technology. This subject paper has (has never) been incorporated in an official NRI Report. James A. Cummings, 7321 (Signature)			
5. ROUTING/APPROVAL			
CODE	SIGNATURE	DATE	COMMENTS
Section Head Branch Head Gregg A. Jacobs, 7320 Division Head Ruth H. Preller, 7300 1226 1006.3 400H Director NCST S. R. Francis, 7000 7000.4 7000.4	[Signatures] Carolyn L. Gilroy	3/31/09 4/1/09 4/6/09	I've got it. Publicly accessible sources used for this publication. <b>This is a Final Security Review</b> Any changes made in the document after approved by Code 1226 nullify the Security Review. 1. Release of the paper is approved. 2. To the best knowledge of the reviewer, the subject matter of this paper does not contain any military critical technology. 3. Subject of this paper is not a trade secret. 4. Subject of this paper is not a trade secret. Sponsor Approved Attached

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# Validation and Intercomparison Studies Within GODAE

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**ABSTRACT.** During the Global Ocean Data Assimilation Experiment (GODAE), seven international operational centers participated in a dedicated modeling system intercomparison exercise from February to April 2008. The objectives were: (1) to show GODAE global-ocean and basin-scale forecasting systems of different countries in routine interaction and continuous operation, (2) to assess the quality and perform scientific validation of the ocean analyses and the forecasting performance of each system, and (3) to learn from this exercise in order to increase interoperability and collaboration in real time. The validation methodology has steadily improved through several validation experiments and projects performed within the operational oceanography community. It relies on common approaches and standardization of outputs, with a set of diagnostics based on fully detailed metrics that characterize its strengths and weaknesses, but it also provides error levels for ocean estimates. The ocean forecasting systems provide daily fields of mesoscale water mass distribution and ocean circulation, with an option for sea-ice variations. We present a subset of the intercomparisons performed over different areas, showing general ocean circulation in agreement with known patterns. We also present some accuracy assessments through comparison with observed data.

## INTRODUCTION

In the MERSEA (Marine Environment and Security for the European Area) Strand1 European Union (EU) framework, a first attempt to intercompare eddy-permitting, basin-scale ocean data assimilating systems was conducted. Hindcasts originating from the different systems were intercompared using climatology and historical high-quality ocean data sets (i.e., World Ocean Circulation Experiment [WOCE] sections) as a reference (Crosnier et al., 2006). In parallel, ocean forecasting systems were developed and improved in several countries as part of, and associated with, the Global Ocean Data Assimilation Experiment (GODAE) community effort (for a detailed description of GODAE, see Bell et al., 2009). While operating continuously, these systems were monitored and compared to a predetermined quality standard. Outputs were either dedicated reanalyses or long simulations, or operational hindcasts, nowcasts, and forecasts. Feedback from these scientific

evaluations were used to improve the systems' components—ocean model parameterization, forcing, or assimilation methodology.

There are more constraints on assessment of ocean analysis and forecasting systems than on validations normally performed for academic projects. The ocean assessments must be performed in real time with practical operational constraints such as computer resources, storage capacity, and availability of reference values (e.g., independent ocean data). Because outputs rely on continuously changing information (e.g., availability of input such as atmospheric forcing fields, in real time), monitoring and assessment of the validation procedures are mandatory.

Outputs from operational systems are also used for commercial and other applications (e.g., oil spills, water-quality assessments, marine security). Thus, the assessment methodology must reflect user requirements. Different applications require different levels of accuracy. For

instance, an ocean model that may be satisfactory for general ocean study may not provide sufficient information for search and rescue activities.

The assessment of data assimilation systems is more focused on accuracy than on overall quality. In other words, where a certain level of quality is sought in pure modeling research (e.g., Is there deep convection? Has Labrador Sea Water formed? Is there a Gulf Stream overshoot, an acceptable meridional heat transport, and meridional overturning circulation?), assimilation experiments are tested on "realistic representation" where reference data are used to directly quantify error levels. A comprehensive error budget is also required for proper assessment of data assimilation results. Assimilation schemes are more or less guided by background and observation errors, and the most sophisticated schemes provide robust forecast error estimates (Brasseur, 2006). It is, then, necessary to verify model error assumptions against dedicated error validation procedures.

In this context, using different model configurations and data assimilation methods, operational oceanography teams have tried to develop their tools for assessing the quality of outputs, and they have started to provide "error bars" to users. Thanks to GODAE, these initiatives could be shared at the international level (Smith, 2006). A special intercomparison exercise was performed at the beginning of 2008 as a GODAE project. The objectives were to: (1) demonstrate GODAE systems in operation, (2) share expertise and design validation tools and metrics endorsed by all GODAE operational centers, and (3) evaluate the overall scientific quality of the different

GODAE operational systems. During the exercise, most operational centers worldwide delivered daily ocean products.

These included:

- BLUElink> (Australia)
- HYbrid Coordinate Ocean Model (HYCOM; United States)
- Meteorological Research Institute (MRI) which developed the Multivariate Ocean Variational Estimation system (MOVE/MRI.COM; Japan)
- Mercator (France)
- Forecasting Ocean Assimilation Model (FOAM; United Kingdom)
- Canada-Newfoundland Operational Oceanography Forecast System (C-NOOFS; Canada)
- Towards an Operational Prediction System for the North Atlantic European Coastal Zones (TOPAZ; Norway).

The next section outlines the assessment methodology. It is followed by a section summarizing the assessment

and intercomparisons performed during GODAE and, particularly, it presents a subset of results from the special intercomparison project.

#### METHODOLOGY OF VALIDATION AND INTERCOMPARISON

The validation methodology performed during the MERSEA Strand1 project (2003–2004), and endorsed at the GODAE level by non-European data assimilation teams, was enhanced during the EU MERSEA Integrated Project (2004–2008). Aspects of the validation methodology specified during the course of this project were: (1) Perform the validation continuously, and thereby stimulate data processing and archiving centers to provide observations in real time. (2) Apply diagnostics that offer robust scientific evaluation of each system, and select the most suitable diagnostics among those applied in research mode. (3) Evaluate both operational

system performance and product quality, taking user requirements into account (usually from short-term to seasonal time-scale applications). (4) Encourage consistency of assessment among the different forecasting centers, applying similar diagnostics to the different systems, thus strengthening the overall assessment management activity through central team expertise. (5) Take advantage of this consistency to allow intercomparison of the operational systems, and thus design and implement technical architecture that allows robust exchanges, interconnections, and interoperability among these systems.

The two last points clearly promote the use of methods and technologies that encourage exchanges and intercomparisons among the different forecasting centers. They also provide impetus for consistently implementing interoperable activities such as ensemble forecasting.

From 2003 to 2008, four test periods allowed different teams to improve the validation and intercomparison methodology. The first intercomparison in the North Atlantic Ocean and Mediterranean Sea during the MERSEA Strand1 project involved five “eddy-resolving” systems (Crosnier et al., 2006; Crosnier and Le Provost, 2007). Conclusions from these test periods permitted: (1) evaluation of system faults, (2) improvements to the different systems, and (3) refinements to the assessment methodology.

Validation procedures developed during MERSEA Strand1 have benefitted operational center developments. Validation procedures were used to verify improvements during upgrades of their systems not only by validating a new system against the former one but

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also by using validation results from the MERSEA Strand1 intercomparison with other forecasting centers to quantify the new system's overall improvements.

The GODAE intercomparison project carried out in 2008 involved the seven global and basin-scale "eddy-permitting" to "eddy-resolving" systems listed earlier. Its focus was on scientific assessment, and it provided a way to improve the assessment methodology for the world ocean, and also offered a first opportunity to intercompare recent systems such as BLUElink<, MOVE/MRI.COM, and C-NOOFS.

The assessment methodology proposed for the GODAE intercomparison project was a direct outcome of previous validation work. Following Crosnier and Le Provost (2007), the assessment had two aspects. First, *the philosophy*: apply a set of basic principles for assessing the quality of MERSEA/GODAE products and systems through a collaborative partnership. Second, *the methodology*: use a set of tools for computing diagnostics and have a set of reference standards for assessing the quality of the products. Both tools and standards must be shareable and usable among the different MERSEA/GODAE members and systems. Both tools and standards should be subject to upgrades and improvements.

The following set of principles was adopted for the assessment:

- Consistency: verifying that system outputs are consistent with current knowledge of ocean circulation and climatologies
- Quality (or accuracy of the hindcast/nowcast): quantifying the differences between the systems' "best results" (analysis) and sea truth, as

estimated from observations, preferably using independent observations (not assimilated)

- Performance (or accuracy of the forecast): quantifying the short-term

vertical discretization).

"Shareability" was the second important aspect of the validation methodology. It allowed each forecasting center to perform intercomparison and

## THE VALIDATION METHODOLOGY HAS STEADILY IMPROVED THROUGH SEVERAL VALIDATION EXPERIMENTS AND PROJECTS PERFORMED WITHIN THE OPERATIONAL OCEANOGRAPHY COMMUNITY.

forecast capacity of each system (i.e., answering the question: Does the forecasting system perform better than persistence and better than climatology?)

A fourth principle was proposed—to verify and take into account the interest and relevance of system outputs for customers, and catch intermediate- or end-user feedbacks:

- Benefit: end-user assessment of the quality level that must be reached before the products are useful for an application

This validation methodology was built using "metrics"—mathematical tools that compute scalar measures from system outputs and compare them to "references" (e.g., climatology, observations). The metrics provide equivalent quantities extracted from the different systems for the same geographic locations. Applied to different forecasting systems, they provide homogeneous and consistent sets of quantities that can be compared without reference to the specific configuration of each system (e.g., horizontal resolution,

validation independently, using results from other centers. Metrics, computed in a standardized way, were stored by each center in order to be available for others. The netCDF file format using the COARDS-CF (Cooperative Ocean/Atmosphere Research Data Service-Climate and Forecast) convention was chosen, allowing time aggregation, easy and flexible manipulation, and self-consistent metadata representation. Distribution relied on Internet communication protocols, basically through FTP. However, more user-friendly communication technologies based on Open-source Project for a Network Data Access Protocol (OPeNDAP) servers that can be visualized through a Live Access Server (LAS), using Dynamic Quick View portals or with similar clients, have now been widely adopted (see Blower et al., 2009). In practice, these technologies allow each forecasting center to compute a considerable amount of diagnostics stored on the local servers of other centers. The total set of validation data does not need to be centralized, which would require large storage capacities.

Instead, for a given diagnostic, one can specifically gather the information spread across the different centers, as shown during the MERSEA Strand 1 project.

Metrics were defined in four types, or “classes,” described below. The consistency and quality of each system could be deduced, or intercompared, from Class 1, 2, and 3 metrics. A system’s performance could be addressed using Class 4 metrics. The “benefit” could also be addressed using a set of Class 1, 2, 3, and 4 metrics. However, new “user-oriented” metrics might need to be defined to fully address the latter.

### Class 1 Metrics

Class 1 metrics aim to provide a general overview of ocean and sea-ice dynamics from the different systems. Ocean and sea-ice model variables corresponding to different horizontal and vertical native grids are interpolated into a common set of horizontal and vertical grids over different regions of the world ocean. Horizontal resolution is selected for an eddy-permitting description of the ocean, whatever the original grid resolution of the different systems (Table 1). Vertical resolution uses the following principal depths: 0, 30, 50, 100, 200, 400,

700, 1000, 1500, 2000, 2500, and 3000 m. These depths do not aim to fully monitor ocean water mass variability, but are a compromise on the storage capacity needed for the world ocean overview.

Class 1 diagnostics present two- and three-dimensional fields. The two-dimensional fields are sea surface height (SSH), wind stress, solar and net heat fluxes, total freshwater fluxes, and mixed-layer depth (MLD); the three-dimensional fields are temperature, salinity, and currents. The diagnostics also present two-dimensional sea-ice variables for mid- and high-latitude

Table 1. Description of regional netCDF Class 1 files. Names, limits and gridding, type of geographical projections, and specific features for each Class 1 area.

	Name	Horizontal resolution		Type of projection	Geographical limits	Specific points
North Atlantic	NAT	1/6°	787 x 597	Mercator	0°–70°N 100°W–31°E	Baltic and Caribbean seas, European shelves, Gulf of Mexico. Sea ice variables.
South Atlantic	SAT	1/6°	601 x 453	Mercator	60°S–0°S 70°W–30°E	Drake Passage, Agulhas Current
Tropical Atlantic	TAT	1/4°	421 x 163	Mercator	20°S–20°N 90°W–15°E	Caribbean seas, Gulf of Guinea
North Pacific	NPA	1/6°	1099 x 518	Mercator	0°–65°N 100°E–77°W	Japan, China seas, Panama. Sea ice variables.
South Pacific	SPA	1/6°	1141 x 453	Mercator	60°S–0° 100°E–70°W	Circum-Australia area
Tropical Pacific	TPA	1/4°	801 x 163	Mercator	20°S–20°N 90°E–70°W	Indonesian seas and straits
Indian Ocean	IND	1/6°	601 x 458	Mercator	20°E–120°E 40°S–31°N	Mozambique Channel, Red and Arabian seas, Bay of Bengal
Arctic Ocean	ARC	12.5 km	609 x 881	Stereo Polar	180°W–180°E 34°N < $\lambda$ < 90°N	North Atlantic Subpolar Gyre; Baltic, Bering, and Okhotsk seas. Sea ice variables.
Southern Ocean	ACC	1/4°	1441 x 937	Mercator	89°S–35°S 0°–360°E	Antarctic Circumpolar Current system, Ross and Weddell ice caps. Sea ice variables.
Mediterranean and Black seas	MED	1/8°	385 x 187	Mercator	6°E–42°W 30N–48°N	Dedicated resolution for the Mediterranean and Black seas.
Global	GLO	1/2°	721 x 359	Regular	180°W–180°E 89°S–90°N	Overview of the world ocean. Sea ice variables.



areas: concentration, ice and snow thickness, and velocity. Class 1 metrics (i.e., daily means) can be used as “instantaneous” estimates of ocean mesoscale circulation for direct comparison to observed quantities, for example, maps of satellite sea surface temperature (SST), satellite altimetry SSH, and dynamic height from synoptic hydrographic data sets. When time-averaged, Class 1 metrics allow “consistency assessment” (i.e., comparison to climatologies or ocean circulation patterns described in the literature).

From Class 1 files, in a given area, one can develop time series of any variable (e.g., temperature, MLD, wind stress) or derived quantities (e.g., eddy kinetic energy), study ocean variability at different depths for different variables (e.g., Hovmuller diagrams of SSH, SST, and Empirical Orthogonal Mode decompositions), and compare these data to equivalent observational data sets (e.g., altimetry sea level maps, SST maps). Spectral analyses can also be performed.

### Class 2 Metrics

Like Class 1, Class 2 metrics were designed to monitor operational system outputs, but in a complementary way. Wherever higher horizontal and vertical resolutions are required, Class 2 metrics provide virtual moorings or sections of the model domain. These specifically chosen sections and moorings represent a reduced amount of stored data and reduce the need to store full three-dimensional fields of the full system domains at high resolution.

Class 2 metrics essentially gather temperature, salinity, currents, and SSH along chosen section tracks and moorings. Sections were sampled horizontally

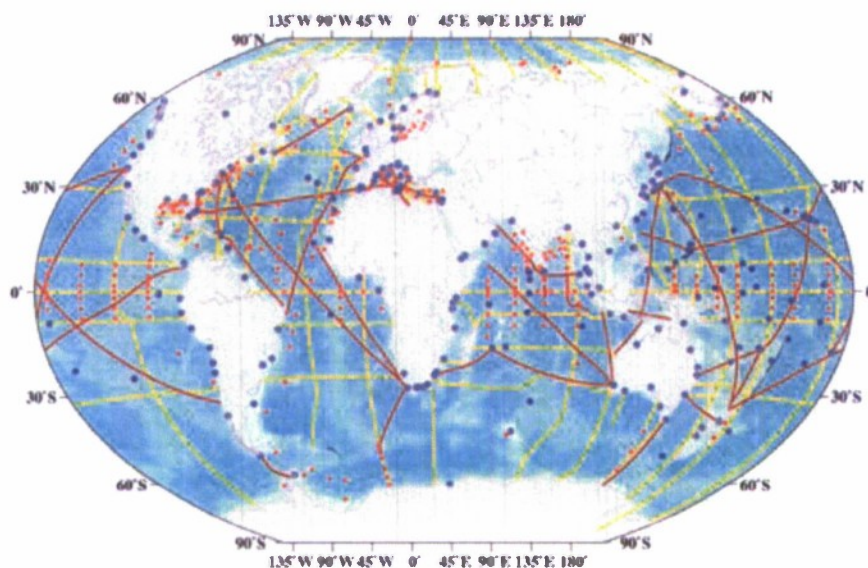


Figure 1. Locations of Class 2 metrics. Yellow = straight sections. Brown = expendable bathythermograph (XBT) sections. Blue = tide gauges. Red = other moorings.

every 10–15 km with a vertical resolution chosen to match standard levels as in the so called “Levitus” World Ocean Atlas 2005 (WOA05; Locarnini et al., 2006) or the Generalized Digital Environment Model (GDEM3.0; Teague et al., 1990) climatologies—78 levels starting with 2-m resolution near the surface, increasing to 250-m resolution in bottom layers.

These sections and moorings were defined to match well-observed regions in order to allow validation, for example, using data from tide gauges, tropical moorings, and current meter moorings that are transmitting in real time, or are serviced regularly. Sections match the most frequently visited expendable bathythermograph (XBT) Ship of Opportunity Programme (SOOP) lines during 2000–2005 as well as the main WOCE and CLIVAR (Climate Variability and Predictability program) repeat sections (Figure 1). Because Class 2 metrics are directly computed online

during the model runs for some systems, their total number is a compromise between computer-time resources and overall description of the world ocean.

Class 2 metrics provide finer knowledge of ocean dynamics and water properties for comparison with in situ or remote-sensing observations. Consistency assessments compare time-averaged Class 2 sections to climatologies, while XBT sections can be compared in near-real time to daily Class 2 sections, allowing the accuracy of daily products to be inferred. Sea-level time series can be validated against tide gauge data. Statistics can also be produced and compared with satellite and other time-series data.

### Class 3 Metrics

Class 3 metrics are derived physical quantities computed using the model variables on the model native grids at each time step that, therefore, cannot be derived from Class 1 or Class 2 metrics.

Typical Class 3 diagnostics are integrated quantities such as daily volume transport through chosen sections, which may coincide geographically with Class 2 sections. Typical Class 3 metrics are: (1) volume transports across chosen sections and total transports as well as, sometimes, transports split into potential temperature, density, salinity, or depth classes; (2) heat transport across sections or meridional heat transport (global, basin-wide) computed similarly to volume transport; and (3) the Overturning Streamfunction (global, basin-wide) as a function of latitude and depth, potential temperature, or potential density.

#### Class 4 Metrics

Class 1, 2, and 3 metrics can be applied to any field produced by the forecasting system (hindcasts, nowcasts, or forecasts). Class 4 metrics aim to measure the performance of the forecasting system, its capability to describe the ocean (in hindcast mode), as well as its forecasting skill (analysis and forecast mode). Class 4 metrics are natural (model-observation) joint products that may be output from the assimilation systems.

Class 4 metrics are limited here to “observational space,” with observations chosen (preferably independent of those used during the assimilation procedure) and compared at all stages of the hindcast-analysis-forecast cycle. Class 4 metrics provide a series of statistics for differences between data and model values for several fields produced by the operational systems, along with observational comparisons to climatology and persistence forecasts. Thus, one can quantify differences in “forecasting skill” for any variable; for example, a

given SSH observation from a tide gauge can be compared to model estimates on that day, or any forecast performed from previous assimilation cycles, or against climatology, or against observation persistence at any time lead. All of these values can be brought together to provide error statistics.

Any data can be used in Class 4 metrics, provided equivalent information can be computed from the model variables. MERSEA Strand 1 compared sea level assessments to satellite altimetry. The MERSEA Integrated Project compared in situ temperature and salinity profiles, sea level from tide gauges, and also satellite sea ice concentrations using Class 4-like metrics. Figure 2 provides an example of sea-ice concentration performance diagnostics computed with the TOPAZ operational system. The sea-ice concentration error, as given by the root mean square (RMS) difference between satellite data and model estimates in a given area, allows quantification of the overall behavior of the system, including the quality of hindcasts, absolute error of forecasts, and forecasting skill relative to persistence.

Again, once model values and equivalent observation quantities are obtained, it is possible to diagnose forecasting system performance on any derived quantity. For instance, from modeled and observed temperature and salinity at any depth, one can plot the  $\theta$ -S diagrams for observed data and climatology, as well as for model three-day forecasts, associated persistence, or analyses. These plots allow one to infer which water masses are well represented in real-time estimates, in predictions, or using climatology or persistence approaches.

Note that performance and forecast

skill can also be inferred in the “model space” by computing statistics on misfits, residuals, and forecast minus analysis. Some examples are given in Cummings et al. (2009).

#### THE GODAE SPECIAL INTERCOMPARISON PROJECT

The seven ocean forecasting systems that participated in the 2008 intercomparison were all “eddy-permitting” or “eddy-resolving,” providing daily estimates and forecasts in real time over the global ocean, or regionally. The three-month period February–April 2008 was chosen because it was the first possible period during which all seven ocean forecasting centers could provide daily averaged hindcast estimates for the Class 1 metrics. The three-month intercomparison period was agreed upon to allow a first assessment from daily to monthly temporal scales. Each system provided estimates over the different regions of their model domains. For each region in Table 1, at least three systems can be intercompared for some Class 1 variables and derived quantities. The assessment of consistency and accuracy relied on real-time in situ or satellite data gathered at the same time in the framework of GODAE.

In this issue, Dombrowsky et al. describe the BLUElink>, FOAM, Mercator, and HYCOM global systems; Hurlburt et al. describe the MOVE/MRI.COM system, the Mercator high-resolution North Atlantic system, the TOPAZ Arctic system, and the C-NOOFS Northwest Atlantic system; and Cummings et al. describe the data assimilation methodology applied by each system. Table 2 summarizes system characteristics. These diverse systems use four types of ocean models, can be



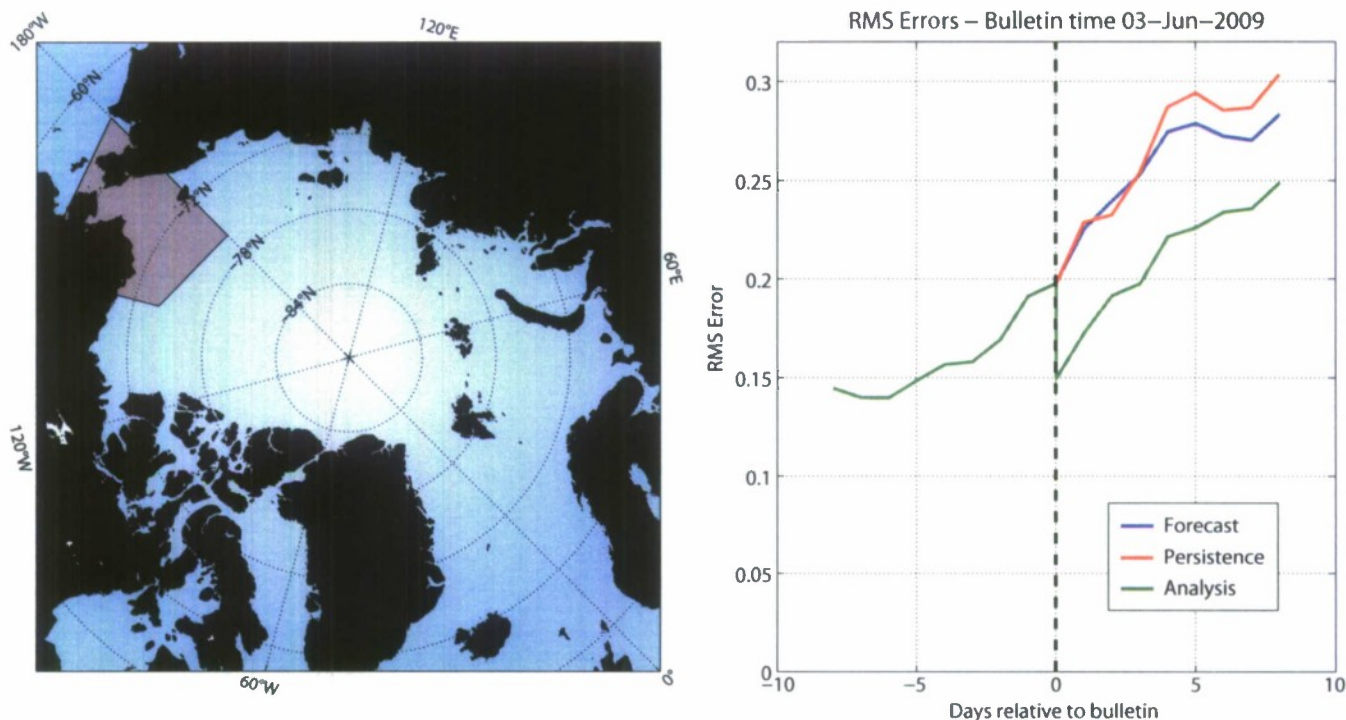


Figure 2. Sea-ice performance diagnostic in the Arctic Ocean. August 2006 to February 2007 root mean square daily differences of sea-ice concentration between Special Sensor Microwave Imager (SSM/I) observed products and the TOPAZ forecasting system are computed for different outputs—analysis and forecasts (1 to 15 days ahead). RMS differences are computed in geographical boxes (left panel, the Bering Strait box), then the averaged performance from hindcast (5 days back) to forecasting 15 days ahead are plotted for analysis, persistence, and forecast (right panel).

global or regional, have different vertical discretizations, are eddy-permitting to eddy-resolving, are coupled or not with sea-ice models, employ different air-sea flux representations, and use different assimilation techniques.

The North Atlantic basin allows comparison of three global systems (HYCOM, FOAM, and Mercator), and three regional systems (TOPAZ, C-NOOFS, and the high-resolution  $1/12^\circ$  Mercator system). The two Mercator systems differ only in their horizontal resolution ( $1/4^\circ$  versus  $1/12^\circ$ ), permitting inference of the impact of higher resolution. All other systems are  $1/4^\circ$  eddy-permitting, except the eddy-resolving  $1/12^\circ$  HYCOM global system.

A water mass analysis was computed for all systems as part of the consistency

assessment. Figure 3 shows comparisons of temperature with WOA05 Climatology (Locarnini et al., 2006) at 30-m depth in February 2008. A general difference pattern shows Labrador Current and East Greenland Current waters colder by  $2^\circ\text{C}$ , waters warmer by  $0.5^\circ\text{C}$  at the eastern boundary, anomalies of  $1\text{--}2^\circ\text{C}$  in the North Sea and southeast of Iceland, and a pronounced difference (larger than  $2^\circ\text{C}$ ) along the African tropical coasts. These results represent real 2008 differences against the climatology. The cold signature in the Labrador Current is associated in most cases with a warmer signature in the inner Labrador Sea, which could indicate a lateral shift or a temperature change in the Labrador Current waters. A negative/positive pattern oriented north/south along the

Gulf Stream could be observed in most of the monthly differences. The position, shape, and thermal content of the Gulf Stream could all be responsible for this difference against climatology; however, the monthly signature of the Gulf Stream was partially different from one system to the other. FOAM and Mercator systems showed similar features, quite different from HYCOM, TOPAZ, and C-NOOFS. Note that the ocean interior exhibits a  $0.5\text{--}1^\circ\text{C}$  colder difference with HYCOM, and the opposite with FOAM. The TOPAZ and Mercator systems have lower warm anomalies. Further accuracy assessment should be made using in situ observation comparisons, as proposed with Class 4 metrics.

SSTs of the forecasting systems were compared with the high-resolution

Table 2. Description of each ocean analysis and forecasting system

System/ assimilation	Ocean model	Configuration	Atmospheric forcing	Assimilated data	Hindcast/ Forecast window
BLUElink>/ BODAS	MOM4.0d	OFAM; Global; 1/10° horizontal resolution around Australia (90°–180°E, south of 17°N); 47 z-levels	6-hour surface fluxes from Bureau of Meteorology	In situ data from GTS and Coriolis + US GODAE; All available altimetric along-track SLA; Australians tide gauge sea level; AMSR-E SST	Twice weekly analysis, 9-day hindcast and 7-day forecast
HYCOM/ NCODA	HYCOM; Los Alamos Ice model (CICE); KPP mixed layer model	Global; 1/12° cos (lat) resolution; hybrid vertical levels 32 $\sigma$ layers	FNOC NOGAPS 0.5° surface fluxes, except NOGAPS 1° precipitation	T/S in situ data; SST from satellite and in situ data; Sea Ice from SSM/I; Altimetric along-track SLA and SST used to produce T/S synthetic profiles	Daily analysis, 5-day hind- cast, 5-day forecast
TOPAZ/ EnKF	HYCOM 2.1.03; EVP; Thermodynamic ice model; KPP mixed layer model	North Atlantic (15°S) and Arctic (Bering Strait); 11–16 km resolution; hybrid vertical levels 22 $\sigma$ layers	6-hour surface fluxes from ECMWF	In situ T/S from Coriolis; weekly altimetric SLA maps from Aviso; RTG SST; Sea Ice concentration; Sea ice drift	Weekly analysis, 1 week back in time, 10-day forecast
Mercator Global PSY3V2/ SAM2V1	NEMO 1.09; LIM2 sea ice model	ORCA02S; Global, 1/4° x 1/4° cos(lat); 50 z-levels, partial steps	Daily mean; ECMWF; Bulk CLIO	In situ T/S from Coriolis; Jason-1, GFO, Envisat along-track SSH; RTG SST	Weekly analysis, 2 weeks back in time hindcast and 2 weeks forecasts
Mercator North Atlantic PSY2V3/ SAM2V1	NEMO 1.09; LIM2 sea ice model	NATL12; Regional Atlantic 80°N–20°S; 1/12° x 1/12° cos(lat); 50 z-levels, partial steps	id	id	id
FOAM/ FOAM	NEMO 1.09; LIM2 sea ice model	Same as Mercator PSY3V2	UK Met. 6-hour surface flux	In situ T/S from GTS; Jason-1, GFO and Envisat along- track SLA; SST OSTIA (GHRSSST); Sea Ice concentration from SSM/I	Daily analysis, 5-day forecast
C-NOOFS/ No assimilation	NEMO 1.09	Regional Northwest Atlantic 103°–27°W, 26°–86°N; 1/4° x 1/4° cos(lat); Nested into Mercator Global PSY3V1; 46 z-levels, partial steps	Hourly Environment Canada surface fluxes (33-km resolution)	Weekly condition of Mercator PSY3 global system	Daily forecast
MOVE/MRI. COM-NP/ MOVE/MRI	MRI.COM; EVP Thermodynamic ice model	North Pacific nested into the global system: 15°S–65°N, 100°E–75°W; 1/2° x 1/2°; 54 levels $\sigma$ -z hybrid coordinates	6-hour surface fluxes from JMA operational outputs	GTS in situ profiles; Jason-1, Envisat along-track SSH; MGDSST	Daily analysis; 1/3-month hindcast



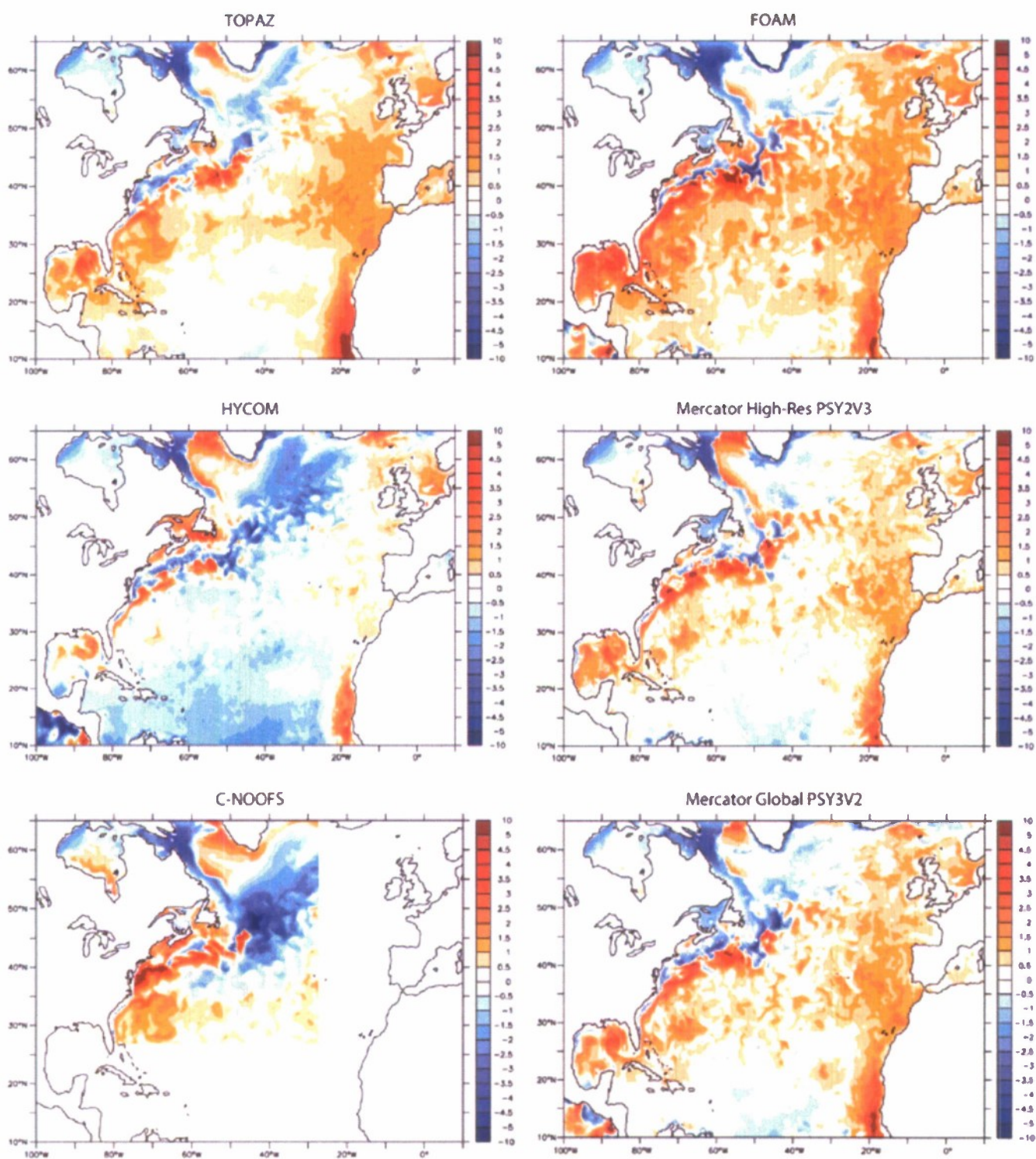


Figure 3. Temperature at 30 m in the North Atlantic area. Monthly mean differences with respect to World Ocean Atlas 2005 (Locarini et al., 2006) climatology in February 2008. Units are  $\pm 5/-5$  in Kelvin.

SST product Operational Sea Surface Temperature and Sea Ice Analysis (OSTIA; see Donlon et al., 2009, for information on OSTIA and other high-resolution SST products developed during GODAE). The OSTIA product's high resolution ( $\sim 6$  km) highlighted errors in the eddy field, demonstrating, in the North Atlantic Ocean, that high-resolution systems such as HYCOM and Mercator provide a better description of the eddy field, even when large-scale biases remain in these systems. Comparison with high-resolution SST observations also identified differences with respect to the climatology coming from interannual variability. At the surface, on average in the North Atlantic (not shown), HYCOM was colder ( $\sim 0.2$  K) and FOAM was warmer ( $\sim 0.4$  K) than OSTIA. These anomalies were reduced in April, indicating that the systems could have been in a "spin-up" process, where assimilation was still reducing surface waters' temperature biases. But the primary use of real-time observed products was intended to provide error levels for ocean forecasting products. Figure 4 illustrates this for the tropical Atlantic. The spatial distributions of RMS differences with OSTIA show that errors in the forecasting systems are not correlated with SST variability itself during the three-month test period. In other words, where SST changed, the systems were able to represent them. For the whole period, FOAM offered slightly better RMS differences compared to the Mercator global product. Because the OSTIA SST product is assimilated into FOAM, this result is expected. HYCOM generally had higher discrepancies north of  $5^{\circ}\text{S}$  on the eastern side of the basin, but the lowest differences north of  $10^{\circ}\text{N}$

on the western side. Box average statistics confirmed that FOAM was slightly warmer than OSTIA SST in the Gulf of Guinea, and warmer in the northern part of the tropical Atlantic, in particular, until April. HYCOM appeared generally too cold. The two Mercator systems showed similar behavior in box averages (with little impact from coarse versus higher horizontal resolution). Differences never exceeded  $1^{\circ}\text{C}$  RMS. All four systems more or less matched the temporal SST changes. Mercator SST changes appeared spatially smoother than those of FOAM and HYCOM, possibly due to the assimilation of low-resolution NCEP/Reynolds SST.

Analysis of heat content showed a wider spectrum of results, where one system could be accurate in one area and present the largest biases in another. The main outcomes at this stage were that water masses present large differences, and all discrepancies (i.e., the level of accuracy) were quantified for all regions. However, to identify the causes of discrepancies both between the forecasting systems and against observations, dedicated analyses need to be carried out by looking at heat transports, air-sea fluxes, ocean mixing, and other variables. The roles of each type of model, assimilation technique, or data set used for assimilation all need to be assessed as causes of the discrepancies. Because Class 1, 2, and 3 metrics allow analysis of heat and buoyancy fluxes as well as heat transports, a dedicated analysis of MLD (based on a temperature criterion difference of  $0.2^{\circ}\text{C}$  from SST) showed large discrepancies among operational system outputs. Again, air-sea fluxes, vertical mixing in the upper ocean layers, and differences in assimilation schemes could all play a role in causing these differences.

Figure 5 is a comparison of water masses at depth. Class 2 sections from the regional MOVE/MRI.COM and the FOAM and Mercator global systems for a given day (April 3, 2008) were compared to salinity reference data from two cruises (April and September 2000). The objectives were to assess the consistency of North Pacific Intermediate Water distributions and to qualitatively identify the main biases at that depth. No large discrepancies were identified. The three assimilation methods, although different, reduced the main biases of these non-eddy-resolving systems, in particular, model errors caused by erroneous vertical/lateral mixing schemes (known problems of most ocean models), and thus they provide three reliable solutions. The distributions of North Pacific Intermediate Waters were similar to observations, although too shallow. Near the surface, at  $45^{\circ}\text{N}$ , the low-salinity patterns showed considerable differences, indicating that a more careful analysis of the mixed layer (freshwater fluxes, mixing, impact of assimilation) would be helpful. Similarly, in the subtropical gyre, representations of North Pacific Tropical Waters with high salinities from 0–200-m depth from the equator toward  $30^{\circ}\text{N}$  were not very realistic.

A careful analysis of the mean kinetic energy (KE) for the three-month period in different areas identified differences in wind-driven circulation patterns. Quality assessment was performed using independent current products, such as Surcouf (Larnicol et al., 2006) or Ocean Surface Current and Analysis in Real time (OSCAR; Johnson et al., 2007), that routinely provide ocean currents near the surface. These products are deduced from satellite altimetry, using geostrophic assumptions, and Ekman current



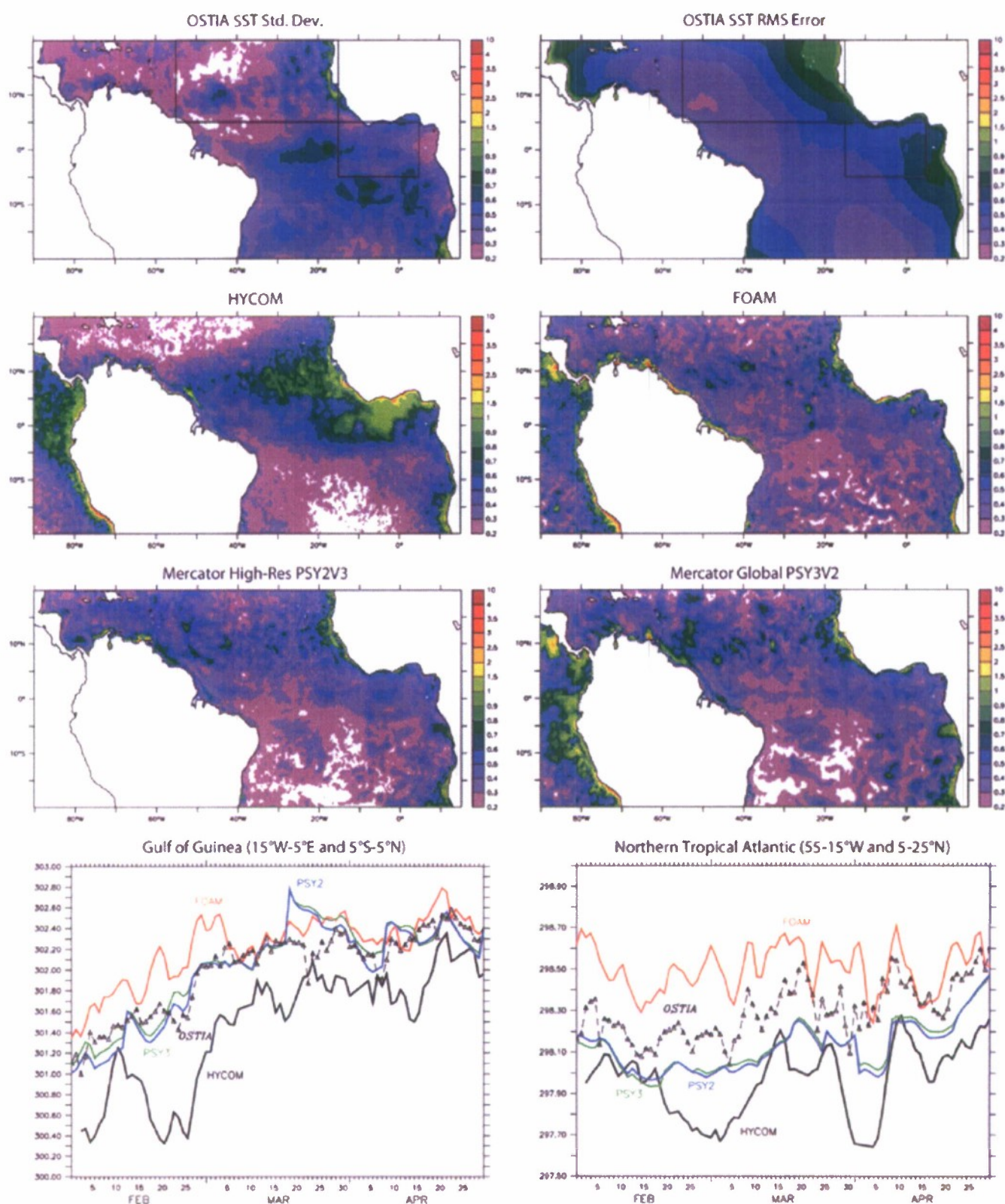


Figure 4. Statistics of sea surface temperature (SST) differences from February 1 to April 30, 2008, in the tropical Atlantic. Top left: Operational Sea Surface Temperature and Sea Ice Analysis (OSTIA) SST standard deviation. Top right: OSTIA SST RMS errors. As labeled, HYCOM (HYbrid Coordinate Ocean Model), FOAM (Forecast Ocean Assimilation Model), and Mercator systems' RMS differences with respect to OSTIA SST are given. Units are 0.2–S Kelvin. Bottom panels: Daily time series of box-averaged SST (Kelvin) from February to April 2008. HYCOM = black. FOAM = red. Mercator PSY2 = blue. Mercator PSY3 = green. The bottom left plots are for a box-limited area in the Gulf of Guinea (15°W–5°E and 5°S–5°N), and the bottom right plots are for a box-limited area in the northern tropical Atlantic (55°–15°W and 5°–25°N). The two areas are plotted in the top left panel.

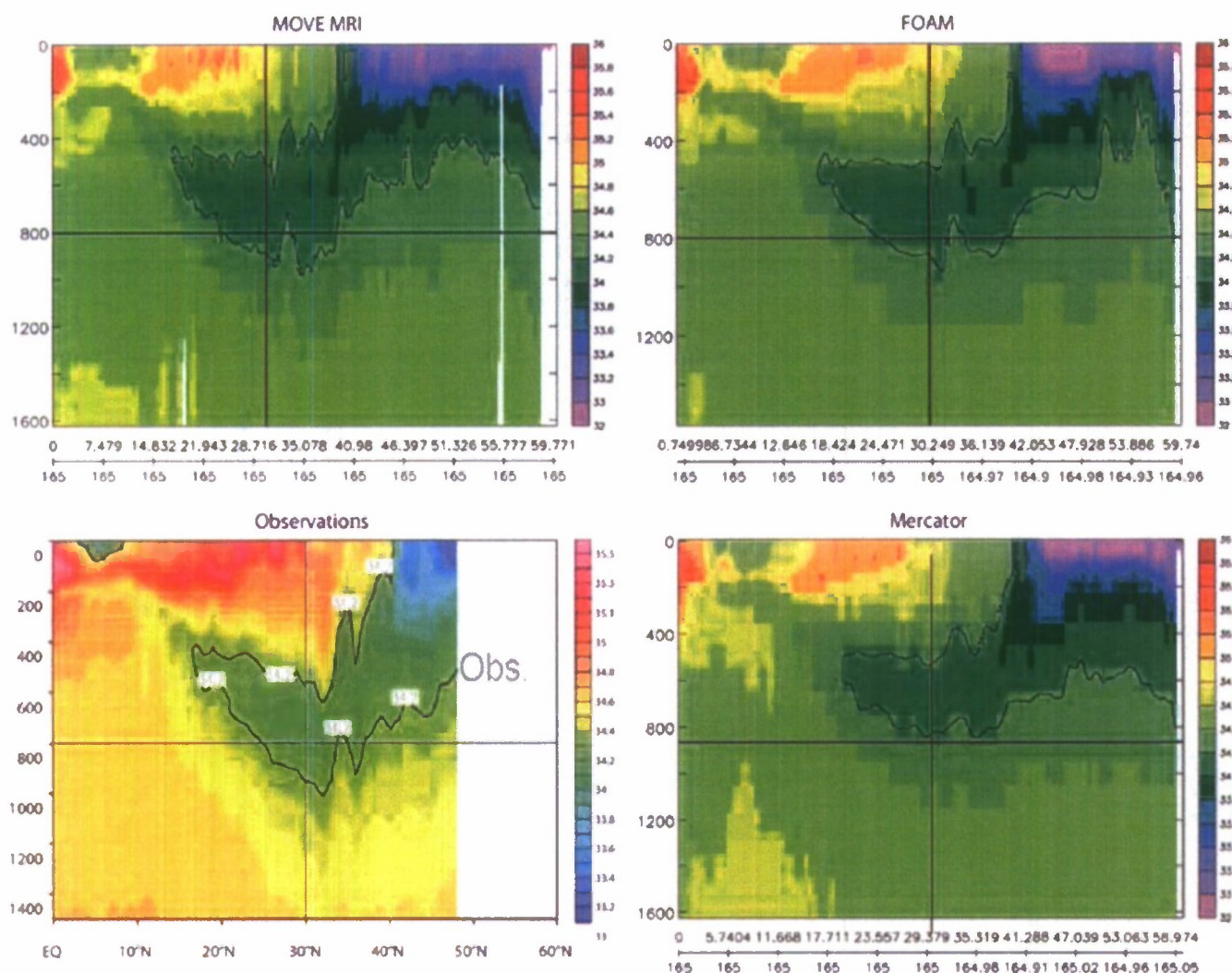


Figure 5. Salinity section comparison (latitude, depth, in practical salinity units) in the North Pacific Ocean at 165°E. Snapshots of MOVE/MRI.COM, FOAM, and Mercator PSY3 Class 2 sections on April 3, 2008, are compared to a composite of CTD data obtained in April 2000. The 34.2 psu isohaline is represented.

estimates from numerical weather predictions or satellite scatterometry. Thus, scales of Surcouf currents used in the comparisons are similar to altimeter-derived information, typically 20–30 km.

Comparisons showed that the HYCOM and Mercator high-resolution systems offered higher mean energy and more consistent patterns than the other systems, confirming the positive impact of the finer horizontal grid, especially within interior or eastern boundary currents. Figure 6 presents eddy field turbulence, as deduced from eddy

kinetic energy (EKE), for Surcouf and the six forecasting systems in the North Atlantic area during the three-month period. Conclusions are similar to the mean current analysis. The FOAM and Mercator global systems give eddy field statistics similar to Surcouf, and Mercator follows most of Surcouf time changes. EKE levels were computed daily in the Gulf Stream box described in Figure 6. Levels are higher but rather similar for the HYCOM and Mercator high-resolution systems, with important variability. C-NOOFS and TOPAZ show EKE at half

the levels of Surcouf EKE. This discrepancy may be due to satellite altimetry assimilation, lacking in C-NOOFS, while TOPAZ ensemble averaging could impact averaged energy levels (about 20% less EKE than individual members, especially in low-energy areas).

A dedicated analysis was performed in the Indonesian throughflow area, where the BLUElink> system, with its high horizontal resolution, could also be compared. Results show that high resolution is key for representing transports through straits and for jets associated



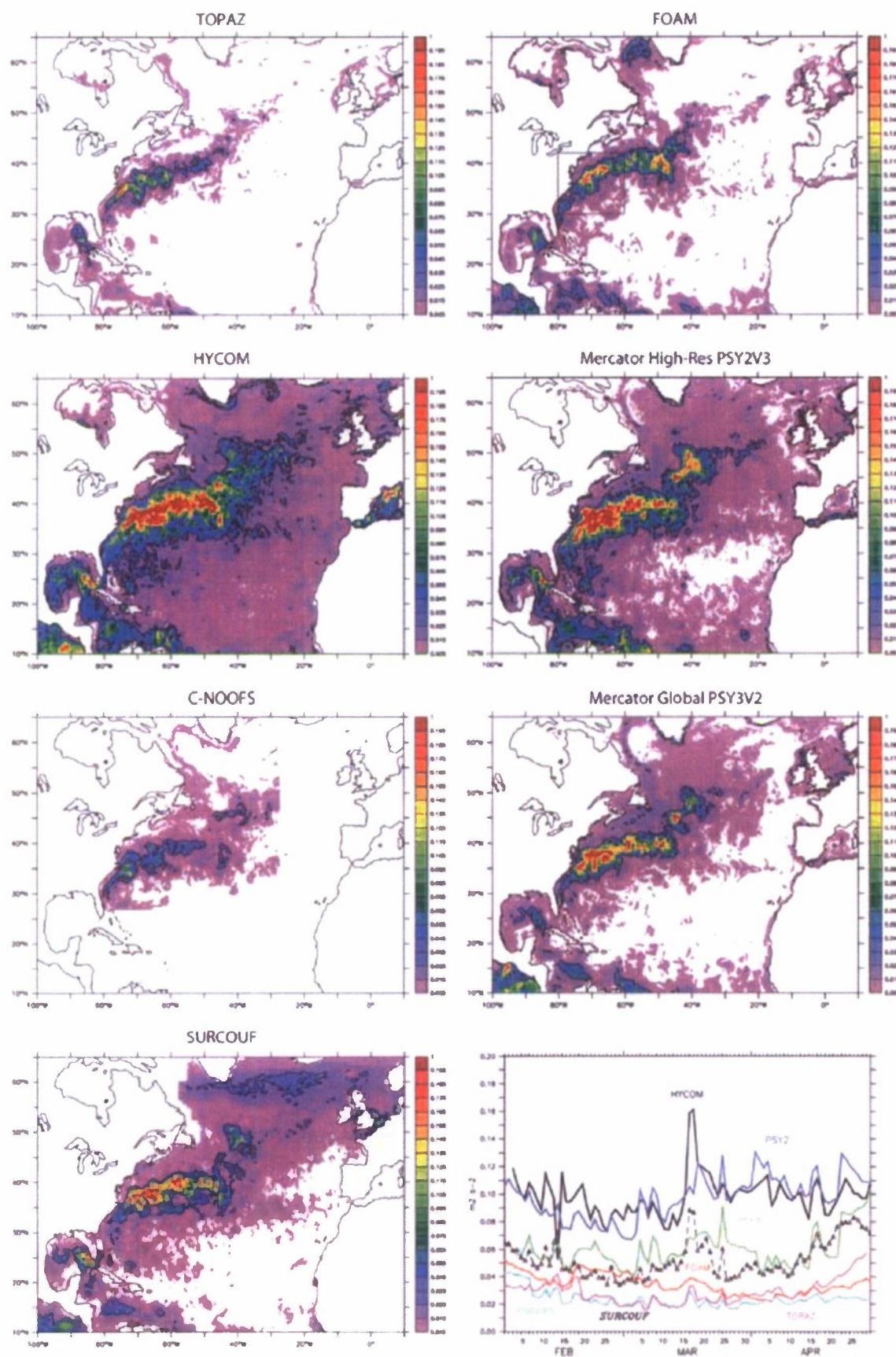


Figure 6. Averaged eddy kinetic energy (EKE) computed from February to April 2008 at the surface for the six forecasting systems, and the Surcouf surface current daily products. The contour line corresponds to  $300 \text{ cm}^2 \text{ s}^{-2}$ . Energy levels from 50 to  $2000 \text{ cm}^2 \text{ s}^{-2}$  are shaded. Bottom right panel: Daily time series of box-averaged eddy kinetic energy in a box-limited area around the Gulf Stream ( $80^\circ\text{--}60^\circ\text{W}$  and  $30^\circ\text{--}42^\circ\text{N}$ , represented in the FOAM map). HYCOM = black. FOAM = red. Mercator PSY2 = blue. Mercator PSY3 = green. TOPAZ = magenta. C-NOOFS = cyan. Surcouf EKE is plotted in a thin black line with symbols. Units are in  $\text{m}^2 \text{ s}^{-2}$ .

with Rossby waves in tropical bands. The impact of bottom friction and drag effects on mixing is clearly evident in the Indonesian marginal seas, where Pacific and Indian waters are mixed differently by FOAM, Mercator, BLUElink>, and HYCOM. Salinity differences in this area could also be caused by mixing effects, although runoff or precipitation errors should not be neglected, and further characterization is needed. Water mass distributions and thermocline depths certainly differ in the eastern Indian Ocean downstream of the Indonesian throughflow. However, even if ocean model parameterization errors are present, assimilation of temperature and salinity data can also reduce the discrepancies and corresponding errors.

## DISCUSSION AND CONCLUSIONS

The GODAE program provided the opportunity to develop an assessment methodology for ocean operational forecasting systems. Most of the operational centers dealing with open ocean, eddy-permitting model and assimilation techniques have been involved in the design and implementation of these assessment tools dedicated to providing scientific validation of forecasting systems and their products.

Consistency, quality, and performance of the operational forecasting systems have been evaluated through several projects. Metrics are now implemented in most of the GODAE ocean forecasting systems, and tools for communicating and exchanging these metrics have been adopted by most of these centers. The GODAE intercomparison project demonstrates the usefulness of these developments. In the near future, this assessment architecture is expected to

be endorsed by the technical panels of the World Meteorological Organization-Intergovernmental Oceanographic Commission Joint Technical Commission for Oceanography and Marine Meteorology.

The GODAE intercomparison project's main outcomes are:

1. Intercomparisons of several systems were conducted that can represent any area of the world ocean.
2. The ocean forecasting systems offer a variety of model (ocean and sea-ice) configurations, and different assimilation techniques and observations were used.
3. Considering the short three-month period for the intercomparison study, ocean dynamics were found to be "consistent" in all systems—the general wind-driven circulation was satisfactorily represented for the boreal winter season, and the assessment over different ocean basins (not fully described in this paper) indicated that thermohaline circulation and water mass distribution were also reasonably represented.
4. The systems were eddy-resolving or eddy-permitting; their day-to-day representations of eddy fields varied, but, statistically, the ocean variability was similar among the systems. There are regional discrepancies that need further analysis with consideration for all system components (e.g., numerical weather prediction forcing, ocean modeling, assimilation techniques, data used).

One important aspect of operational validation not emphasized here is the key role played by observations (a comprehensive presentation of the global ocean observing system is provided by Clark et al., 2009). There is no doubt that the

validation methodology could only be successfully applied because observational projects promoted by GODAE, such as Argo (Roemmich et al., 2009) and Global High-Resolution Sea Surface Temperature (GHRSSST; Donlon et al., 2009), provide sufficient data in real time. Moreover, the data archiving and assembly centers such as US GODAE and Coriolis, among others, play an important role, providing for the robust distribution of data in real time.

The set of tools and metrics that GODAE leaves as a legacy should be linked with several applications and activities. The CLIVAR Global Synthesis and Observation Panel aims to develop added value to long-term simulations and reanalyses of the ocean, setting up dedicated diagnostics over different basins. Coupled ocean-atmosphere models used for seasonal and longer forecasting are also validated using specific diagnostics. These different communities can benefit from GODAE metrics in order to verify consistency with operational ocean systems. These longer simulations are often performed inside operational centers using the same ocean model configuration used for short-term predictions. Observing system experiments based on an operational model configuration can also rely on GODAE metrics for assisting impact studies (see review by Oke et al., 2009). As downscaling becomes a more systematic approach to forecasting in coastal areas and regional seas, this set of GODAE metrics can be used in two ways: (1) to aid in the design of dedicated metrics for coastal areas following the methodology presented in this paper or by applying GODAE metrics directly to regional systems, thus allowing intercomparison between large-scale



and downscaled operational systems (see De Mey et al., 2009), and (2) by the biogeochemical community, where most biogeochemical models are now being coupled to the physical ocean forecasting systems described here.

The GODAE intercomparison project focused mainly on scientific validation of operational products. The end-to-end system assessment, as tested in the MERSEA integrated project, was not emphasized among GODAE activities, that is, to design, implement, and test diagnostics that monitor the robustness of daily operations and detect failure and faults that could impact the quality of operational ocean estimates and forecasts in real time (e.g., lack of a particular set of satellite data during a given day, or most recent atmospheric forcing). However, in the near future, new European initiatives in the framework of the Global Monitoring for Environment and Security program, like the MyOcean project that attempts to define the future of operational oceanography in Europe, will endorse the need for the GODAE validation methodology.

#### ACKNOWLEDGEMENTS

The European Commission provided financial support to develop TOPAZ systems in the DIADEM/TOPAZ projects, and to develop FOAM, Mercator, MFS, and TOPAZ systems in MERSEA Strand1 (Contract no. EVK3-CT-2002-00089) or the MERSEA Integrated Project (Contract no. SIP3-CT-2003-502885) and BOSS4GMES projects. TOPAZ uses a CPU grant from the Norwegian supercomputing project (NOTUR). The French Mercator Océan systems were implemented with financial support from the Région Midi Pyrénées. The US effort was supported by the

project US GODAE: Global Ocean Prediction with the HYbrid Coordinate Ocean Model (HYCOM), funded under the National Oceanographic Partnership Program, by the Office of Naval Research 6.1 project Global Remote Littoral Forcing via Deep Water Pathways under program element 601153N, and by grants of computer time from the US Department of Defense High Performance Computing Modernization Program (HPCMP). The Australian BLUElink science and technical team was supported by the Bureau of Meteorology, CSIRO, Wealth from Oceans National Research Flagship, and the Royal Australian Navy. The Japanese GODAE effort was supported by JMA/MRI and by Category 7 of the MEXT RR2002 Project for Sustainable Coexistence of Humanity, Nature, and the Earth. ■

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